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Programming suite RDE	page 26



headquarters, Castelletto S. Ticino NO









Company Profile

Robox S.p.A, a company started in 1975, designs and manufactures electronic controllers, programming languages, development environments for robotics and motion control systems. Its broad range of products can be adapted to any application, from the simplest ones (1 or 2 controlled axes), to the most sophisticated ones (dozens of controlled axes) thanks to the availability of architectures which can be "modular", "compact" or even integrated in brushless drives. Robox controllers communicate with the outside world through the main industrial communication protocols and fieldbuses (EtherCAT, Sercos, OPCUA, ActiveX, TCP, UDP, TFTP, ČANopen, Profibus-DP, DeviceNet, DF1, Profinet slave, Ethernet/IP, Modbus/TCP).

Innovation and quality have been the main goals of Robox since the very beginning. Innovation has always been pursued keeping in mind the global reliability (present and future) of the product. Quality has always been ensured by appropriate design choices and an accurate selection of materials. Robox has been certified UNI EN ISO 9001 since 1997.

Robox is a highly specialized research laboratory authorized by the Italian Ministry of Research and Education.

Goals achieved:

- 1976 first micro-processor based controller for industrial robots (Intel 8080)
- 1984 first programming language for the "robot control" (Robox RHLL)
- 1986 first compact Motion controller RPM (Intel 80186)
- **1987** first programming language for the "Motion control" (Robox R)
- 1993 first integrated development environment for Windows (Robox RDE)
- 1997 first modular Motion controller RBXM (Intel 80486)
- 1999 Profibus DP, DeviceNet for Robox Motion controllers
- 2000 Master CANopen for Robox Motion controllers
- 2000 Positioning board for MOOG DACS Drive
- 2001 TCP/IP, UDP/IP protocol for Robox Motion controllers
- 2001 CANopen slave interface for SIEMENS SIMODRIVE
- 2002 RDE3 evolution of the Robox development environment
- 2003 CPU based on Freescale Power PC G2 for RBXM
- 2004 RTE operating system
- 2005 CANopen slave interface for SIEMENS SINAMICS S120
- 2006 Motion control board for PARKER Hannifin
- 2007 EtherCAT slave interface for PARKER Hannifin
- 2007 µRMC based on Freescale Power PC G2
- 2008 SPIMD20 for STMicroelectronics
- 2008 EtherCAT master for Robox Motion controllers
- **2009** EtherCAT slave interface for PHASE
- 2009 µRMC² based on Freescale Power PC G2
- 2009 SERCOS 2 interface
- 2010 CPU based on the Freescale Power PC P2020 for RBXM
- 2011 µRMC³ based on Freescale Power PC P2020
- 2011 RID20 Robox Integrated Drive
- 2012 Profinet slave, Ethernet/IP, Modbus/TCP
- **2013** µRIO, ROS (Robot Operating System)
- 2014 RFBCED Ether Cat Net graphic configurator
- 2015 RP-1 based on Freescale Power Pc (400Mhz)
- 2015 RID20-I
- **2016** RPL (Robot programming language)
- 2017 Integration of SafetyBridge Axioline modules
- 2017 RP-2 based on ARM Cortex A9 (800Mhz)
- 2018 EtherCAT slave interface for SIEMENS SINAMICS S120
- 2018 EC2A 6 axes intelligent drive
- 2018 RIG8 Teach pendant unit
- 2018 RP-0 based on ARM Cortex A9 (600MHz)
- 2019 Safety Board for Robotics
- **2020** EC2B 6 axes intelligent drive
- 2021 RID20-E Robox Evolution Integrated Drive
- 2021 R++ object oriented structured text language
- 2021 Axioline Stepper Module (Smart Element)
- 2021 Natural Guidance for AGV
- 2022 MEMS-based guidance for AGV
- 2022 OPC UA protocol for RP-2
- **2023** G-code language
- 2023 EtherCAT slave interface for RP-2
- 2024 µRP-2 based on ARM Cortex A9 (800MHz)
- 2024 EEBE board for advanced safety functions
- 2025 SI- μPAC based on AMR Cortex A9 (600 MHz) for Nidec drives
- 2025 RTEMS multicore operating system

technical office, Genova

2



3

Application fields

The main application fields for Robox Motion controllers are:

- Beverage
- Packaging
- Palletizing/depalletizing devices
- Glass industry machines
- Food industry machines
- Wood industry machines
- Hygiene industry
- Tissue industry
- Paper industry machines
- Plastic industry machines
- Textiles industry machines
- Marble industry machines
- Automated guided vehicles (AGVs)
- Feeding devices
- Painting robots
- Measurement machines
- Machines for fibre optic handling
- Printing machines
- Winding machines
- Robots
- Spot welding robots
- Arc welding robots
- Assembly robots
- Plasma cutting robots
- Laser cutting robots
- Water jet cutting robots
- Glue application robots
- Pick & place robots
- Automatic warehouses
- Machine tools
- etc.



PLASTIC INDUSTRY MACHINES



MARBLE INDUSTRY

MACHINES





WOOD INDUSTRY MACHINES

Application fields

BEVERAGE



AGV

PACKAGING



FOOD INDUSTRY MACHINES





PALLETIZING / DEPALLETIZING DEVICES

Application fields







RP-2 product specification

- ARM Cortex A9 Dual Core (800MHz)
- Up to 32 interpolated axes, driven through EtherCAT and/or CANopen fieldbus
- Suitable for installation on DIN guide (35mm)
 Watch dog relay in accordance with EN60715 rule
- External measures (I, h, p): 100 x 123 x 96 (mm) 0.5Kg
- Micro SD flash memory / 1GB DRAM / 512KB
 UL certification

Communication

- 2 10/100 Mbits/s Ethernet channels dedicated to master fieldbus (EtherCAT CoE, SoE, EoE) for axes control and/or remote I/O
- 2 10/100 Mbits/s Ethernet channels dedicated to slave fieldbus EtherCAT and PROFINET
- 2 10/100 Mbits/s Ethernet channels with internal switch for general purposes (TCP/IP, • 1 Wan channel for factory level access UDP, TFTP, Modbus/TCP, Ethernet/IP, Robox BCC/31/TCP, OPCUA) * 4 for AS1018.003
- 1 10/100 Mbits/s Ethernet channel with Wan function
- 1 Wi-Fi channel for general purposes
- 1 Canbus channel (Master DS301, DS401

Expansion boards

Axioline peripherals See section "Expansion modules/Remote I/O"

RTE Firmware (Real Time Extended)

It is installed in the removable MicroSD card
and allows the correct execution of the different tasks
The available tasks are the following:
On event (capture)priority 1
 Programmed frequency (motion)priority 2
• Programmed frequency (auxiliary functions)priority 3,4,5,6
Backgroundpriority 7
OB hookedpriority 2
OB hookedpriority 5
The user develops the application software using RDE
(Robox Development Environment)
See section "Programming suite RDE"

Product codes

- **Motion Controller**
- RP-2 AS1018.002
- RP-2 (Bus slave) AS1018.012
- RP-2 AS1018.003

Compact flash

- MicroSD (<=3axes) RP AS3025.306
- MicroSD (<=4axes) RP AS3025.308
- MicroSD (<=5axes) RP AS3025.309
- MicroSD (<=8axes) RP AS3025.305 MicroSD (<=10axes) RP - AS3025.310

RP-2

retentive RAM (for retentive parameters and alarm history storage) Real time clock calendar

• 128X64 OLED display for diagnostics and monitoring of the CPU status equipped with five degrees range joystick



and DS402 protocols for axes control and/or remote I/O, Device Net, Robox Cnet)

• 1 USB type B - UART serial channel for general purposes (Robox BCC/31, DF1)

• 1 RS232 serial channel for general purposes (Robox BCC/31, DF1)

• OPC Server, ActiveX, rLibJava, rLibQt, RlibNet and rLibC available for communication in Windows environment

 Axioline master bus for Axioline F modules Diagnostic web server

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		Service Index
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 MicroSD (<=12axes) RP - AS3025.307 MicroSD (<=16axes) RP - AS3025.304 MicroSD (<=32axes) RP - AS3025.303 • MicroSD (AGV) RP - AS3025.313



RP-1 product specification

- Freescale Power PC MPC5200 (400MHz)
- Up to 32 interpolated axes, driven through CANopen or EtherCAT fieldbus
- Suitable for installation on DIN guide (35mm) in accordance with EN60715 rule
- External measures (l,h,p): 100 x 123 x 96 (mm) 0,5 kg
- Compact flash memory Card / 64 MB DRAM /
 Watch dog relay
 Display for monit
 and alarm history storage)
 UL certification

Communication

- 2 10/100 Mbits/s Ethernet channels (EtherCAT, 1 CoE, SoE, EoE for axes control and/or remote I/O, TCP/IP, UDP, TFTP, Modbus/TCP, Ethernet/IP, Robox BCC/31/TCP)
- 2 Canbus channels (Master DS301, DS401 and DS402 protocols for axes control and/or
 remote I/O, Device Net, Robox Cnet)
- 1 Profibus channel (DP slave)
- 1 RS232 serial channel for general purposes (Robox BCC/31, DF1)

Expansion boards

Axioline peripherals See section "Expansion modules/Remote I/O"

RTE Firmware (Real Time Extended)

It is installed in the removable Compact F and allows the correct execution of the d	
The available tasks are the following:	
On event (capture)	priority 1
 Programmed frequency (motion) 	priority 2
 Programmed frequency (auxiliary function 	ns)priority 3,4,5,6
Background	priority 7
OB hooked	priority 2
OB hooked	priority 5
The user develops the application softwa	re using RDE
(Robox Development Environment)	
See section Programming suite I	RDE

Product codes

Motion Controller

RP-1 - AS1017.004

Compact flash

- CompactFlash (<=3axes) RP-1- AS3023.306
- CompactFlash (<=4axes) RP-1- AS3023.308
- CompactFlash (<=5axes) RP-1- AS3023.309
 CompactFlash (<=8axes) RP-1- AS3023.305
- CompactFlash (<=8axes) RP-1- AS3023.305
- CompactFlash (<=10axes) RP-1- AS3023.310

RP-1

Expandable motion controller: RP-1

8 digital, PNP, 24VDC opto-coupled inputs (3 with capture functions)
8 digital, PNP, 24VDC opto-coupled outputs (max 0.5A per channel)
1 incremental encoder input (RS422 line driver 5VDC) with dedicated homing input
Real time clock calendar
Watch dog relay
Display for monitoring the Cpu status
UL certification

1 RS422/485 serial channel for general purposes (Robox BCC/31, DF1)
OPCServer, ActiveX, rLibJaya, rLibQt, RlibNet and rLibC available for communication in Windows environment
Axioline master bus for Axioline F modules
Diagnostic web server

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 • CompactFlash (<=12axes) RP-1- AS3023.307</td>

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 • CompactFlash (<=16axes) RP-1- AS3023.304</td>

 .309
 • CompactFlash (<=32axes) RP-1- AS3023.303</td>

 .305
 • CompactFlash (AGV) RP-1- AS3023.313

 3.310



RP-0 product specification

- ARM Cortex A9 (600MHz)
- Up to 5 interpolated axes, driven through EtherCAT and/or CANopen fieldbus
- Suitable for installation on DIN guide (35mm) Watch dog relay in accordance with EN60715 rule
- External measures (I, h, p): 100 x 123 x 96 (mm) 0.5Kg
- Micro SD flash memory / 1GB DRAM / 512KB
 UL certification

Communication

- 2 10/100 Mbits/s Ethernet channels (EtherCAT, 1 USB type B UART serial channel for general CoE, SoE, EoE for axes control and/or remote I/O, TCP/IP, UDP, TFTP, Modbus/TCP, Ethernet/IP, • OPC Server, ActiveX, rLibJava, rLibQt, Robox BCC/31/TCP)
- 1 Canbus channel (Master DS301, DS401 and DS402 protocols for axes control and/or • Axioline master bus for Axioline F modules remote I/O, Device Net, Robox Cnet)

Expansion boards

See section "Expansion modules/Remote I/O"

RTE Firmware (Real Time Extended)

It is installed in the removable MicroSD card and allows the correct execution of the different tasks The available tasks are the following:
On event (capture)priority 1
Programmed frequency (motion)priority 2
• Programmed frequency (auxiliary functions)priority 3,4,5,6
Backgroundpriority 7
OB hookedpriority 2
OB hookedpriority 5
The user develops the application software using RDE
(Robox Development Environment)
See section "Programming suite RDE"

Product codes

Motion Controller • RP-0 - AS1018.000

Compact flash

- MicroSD (<=3axes) RP AS3025.306
- MicroSD (<=4axes) RP AS3025.308 MicroSD (<=5axes) RP - AS3025.309

RP-0

retentive RAM (for retentive parameters and alarm history storage) Real time clock calendar

• 128X64 OLED display for diagnostics and monitoring of the CPU status equipped with five degrees range joystick



purposes (Robox BCC/31, DF1)

RlibNet and rLibC available for communication in Windows environment

• Diagnostic web server

Expandable motion controller: RP-0

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AXI-F-BP-SE6 Axioline F Backplane, 6 slots for Axioline Smart Elements,



AXL-F-BP-SE4

Axioline F Backplane, 4 slots for Axioline Smart Elements, transmission speed in the local bus

IP 67 modules



AXL-E-EC-DIO16-M12-6P Axioline E- EtherCAT® device in a plastic housing with 8 inputs, 24 V DC, 8 outputs, 24 V DC, 500 mA, M12 fast connection technology



AXL-E-EC-DI8-DO8-M12-6P

transmission speed in the local bus

Axioline E-EtherCAT" device in a plastic housing with 16 configurable inputs or outputs, 24 V DC, M12 fast connection technology



AXL-E-EC-IOL8-DI4-M12-6P Axioline E-EtherCAT® device in a plastic housing with 8 IO-Link ports and 4 digital inputs, 24 V DC, M12 fast connection technology

Expansion modules / Remote I/O Serie F

Digital input/output modules



Analog input/output modules

AXL-F-AI4-I-1H Axioline F analog input module, 4 inputs: 0 - 20 mA, 4 - 20 mA, ±20 mA, 2, 3, and 4-conductor connection technology, integrated sensor supply



AXL-F-AI4-U-1H Axioline F analog input module, 4 inputs: 0 - 5 V, \pm 5 V, 0 - 10 V, \pm 10 V, 2, 3, and 4-conductor connection technology, integrated sensor supply

method

AXL-F-AI8-1F Axioline F analog input module, 8 inputs: 0 - 10 V, ±10 V, 0 - 20 mA, 4 - 20 mA, ±20 mA, 2-wire connection

Temperature modules

AXL-F-RTD4-1H

Axioline F temperature module, 4 inputs for connecting resistance temperature detectors



AXL-F-RTD8-1F Axioline F temperature module, 8 inputs for connecting temperature shunts

Special function modules

AXL-F-CNT2-INC2-1F

Axioline F special function module, 2 counter inputs, 2 incremental encoder inputs

AXL-F-PWR-1H Axioline F power module for the communications power UBus, max, 4 A



AXL-F-PM-EF-1F Axioline F power measurement module, input voltage: up to 400 V AC (phase/neutral) or 690 V AC (phase/phase), input current: up to 5 A AC



AXL-F-RS-UNI-1H Axioline F communication module for serial data transmission, 1 interface can be parameterized as RS.485/ RS-422 or RS.232

Safety modules



AXL-F-SSDI8/4-1F Safety-related digital input module, IP20 protection, for the SafetyBridge system. The module has 4 safe digital inputs for two-channel assignment or 8 safe digital inputs for single-channel assignment.



AXL-F-SSDO8/3-1F

Safety-related digital output module, IP20 protection, for the SafetyBridge system. The module has four safe digital outputs with two-channel occupancy or 8 safe digital outputs with single-channel occupancy



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1	AXL-F-D Axioline mA, 1-w
1	AXL-F-D Axioline mA, sing
11	AXL-F-D Axioline single-w
	AXL-F-D Axioline 24 V DC connecti
1	AXL-F-D Axioline V DC, 10

DO16/1-1H e F digital output module, 16 outputs, 24 V DC, 500 vire connection method

DO32/1-1F e F digital output module, 32 outputs, 24 V DC, 500 gle-wire connection method

DO32/1-2H F digital output module, 32 outputs, 24 V DC, vire connection method

DI8/1-DO8/1-1H F digital input and output module, 8 inputs, , 8 outputs, 24 V DC, 500 mA, single-conductor ion technology

DI16/1-DO16/1-2H F digital input and output module, 16 inputs, 24 16 outputs, 24 V DC, 500 mA, 1-wire connection technology

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AXL-F-AO4-1H Axioline F analog output module, 4 outputs: 0 - 10 V, ±10 V, 0 - 5 V, ±5 V, 0 - 20 mA, 4 - 20 mA, 2-wire connection technology

AXL-F-AO8-1F Axioline F analog output module, 8 outputs: 0 - 10 V, ±10 V, 0 - 5 V, ±5 V, 0 - 20 mA, 4 - 20 mA, ±20 mA, 2-wire connection technology

AXL-F-AI2-AO2-1H Axioline F analog input and output module, 2 inputs, 2 outputs, 0 - 10 V, ±10 V, 0 - 5 V, ±5 V, 0 - 20 mA, 4 -20 mA, ±20 mA, 2-conductor connection technology

	AXL-F-UTH4-1H Axioline F temperature module, 4 inputs for connection of thermocouple sensors
1	AXL-F-UTH8-1F Axioline temperature module, 8 inputs for connection of thermocouple sensors

-	AXL-F-PWM2-1H Axioline F, function module, pulse width modulation, transmission speed in local bus 100 Mbps, IP20 degree of protection, including bus base module and Axioline F male connectors
. 7	AXL-F-SSI1-AO1-1H Axioline F function module, 1 SSI interface for absolute encoder, 1 analog output: 0 - 10 V, ±10 V, 0 - 5 V, ±5 V, 0 - 20 mA, 4 - 20 mA, ±20 mA, 2-conductor connection technology
1	AXL-F-SGI2-1H Axioline F, strain gauge capture module, Transmission speed in the local bus: 100 Mbps, degree of protection: IP20. including bus base module and Axioline F

re module, Transmission ops, degree of protection: le and Axioline F connectors



AXL-F-LPSDO8/3-1F

Safety-related digital output module, IP20 protection, for the SafetyBridge system. The module has four safe digital outputs with two-channel occupancy or 8 safe digital outputs with single-channel occupancy

Expansion modules / Remote I/O Serie SE

1/0

Programmable Safety PLC



AXL-SE-SC-A Axioline Smart Elements slot cover, diagnostic function

Digital input/output modules



AXL-SE-DI16/1 Axioline Smart Elements digital input module, 16 inputs, 24 V DC, connection technology

AXL-SE-DO16/1 Axioline Smart Elements digital output module, 16 inputs, 24 V DC, connection technology

Analog input/output modules



AXL-SE-AI4-I-4-20 Axioline Smart Elements analog input module, 4 inputs , 4 mA ... 20 mA, connection technology

AXL-SE-AI4-U-0-10 Axioline Smart Elements analog input module, 4 inputs, 0 V ... 10 V, connection technology

AXL-SE-AO4-I-4-20 Axioline Smart Elements analog output module, 4 inputs, 4 mA ... 20 mA, connection technology

AXL-SE-AO4-U-0-10 Axioline Smart Elements Analog output module, 4 inputs, 0 V ... 10 V, connection technology

Temperature modules

AXL-SE-RTD4-PT100

Axioline Smart Elements temperature recording module, 4 analog RTD inputs,connection technology



AXL-SE-UTH4-EF

Axioline Smart Elements, Temperature recording module, Analog inputs: 4 (Inputs for thermocouples or linear voltage), connection technology: 2-conductor (shielded, twisted pair), External cold junction (can also be used as an additional Pt 100 sensor input): 1, connection technology: 4-conductor, degree of protection: IP20

Special function modules



Safety modules



AXL-SE-SSDI8/3 Axioline Smart Elements digital input module, IP20 protection, SafetyBridge system. Safe digital inputs: 8 (1-channel assignment), 4 (2-channel assignment), 24 V DC, connection technology: 3-conductor



AXL-SE-SSDO4/2-2A Axioline Smart Elements digital output module, IP20 protection SafetyBridge system, Safe digital outputs: 4 (1-channel assignment), 2 (2-channel assignment), 24 V DC, 2 A, connection technology: 2-conductor

AS8001.001 (RO-AXL SE STP2)

controller

Axioline Smart Element dual channel stepper motor



SAFE ROBOTICS

High safety standards must be observed when humans and robots work together in the same area. Any risk of injury to humans must be completely eliminated. The development of new safety components for safe humanrobot interaction is one of our main areas of research.

SSCU-1









Thanks to FSoE technology, and Safe Advanced Aritmetics (SARC), the Safety PLC line can perform safe encoder reading and monitor safe position, velocity and behaviour of complex dynamic robotics systems. This solution can also interact dynamically with the area configuration of safety scanners and monitor the area surrounding robots and moving vehicles in a safety certified way.

The system is fully customizable to perfectly fit the requirements of each specific system.



SAFE AGVS

To ensure processes in the production area and in logistics, it is often necessary to monitor not only the speeds and position but also the environment of automated guided vehicles (AGV).

ROBOX by BBH

Open programmable and configurable FSoE Master unit for operation on EtherCAT networks

- Data interface for up to 6 scanner units
- 4 Encoder interfaces (only for SSCU-1/AX)
- 16 Safe digital inputs
- 10 Safe digital outputs
- 2 Relay outputs
- 2 Configurable pulse outputs or safe digital outputs
- Safety controller suitable up to PL e (EN ISO) 13849-1) or SIL3 (IEC 61508)
- Optional: SARC functionality (Safe Arithmetic Calculation)
- cULus approval

rogrammable Safety PLC





> RPC family



> RHMI family



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> RIG8

RPC - AS6012.XXX

RPC are a family of industrial PCs, based on a fanless INTEL processor suitable for producing sophisticated operator interfaces aimed to facilitate the use of the machine controlled by the end user. By using the RDT software, interaction is possible, through the BBC3 Protocol on support TCP / IP, with the motion controller connected both with variable exchange as well as with upload / download of files. The terminal is furthermore equipped with an integrated remote service software which renders its Internet access, particularly simple and quick.

Product specification:

- Display LCD TFT from 10 inches up to 15 inches
- CPU Intel Atom dual core 1,86 GHz
- 2 GB DDR3 dynamic ram
- SSD drive 32GB 2,5" SATA MLC
- CFast 2GB SATA 2 SLC
- •. 2 expansion slot MiniPCI
- 1 USB frontal port 4 USB ports
- 1 serial port RS232
- 1 PS/2
- 2 Ethernet interface 10/100/1000 Mbps
- Power supply 24VDC

Programming:

- RTM run-time software to execute RDT projects
- REMOTE SERVICE software via VPN
- User friendly configurator

RIG8 - AS6014.001

Product specification:

- 8" colour TFT LCD touch screen display 1024X768
- CPU: ARM® Cortex® A9
- Mass Memory eMMC: 4GB
- Keybord right side: 18 buttons
- Keybord botton side: 10 buttons
- · Led: One led tri-color red-green-yellow
- Emergency button: double contact
- Enable button: double contact, 3 state
- Connection cable 8m
- Kernel: Linux
- External measures: mm 275*232*106, 1 Kg

RDT - Programming software to design your HMI

RDT is an RDE plug-in, allowing to design customized HMI's (Human Machine Interface).

- It offers the user a set of controls such as:
- Customizable operating push-buttons ComboBox
- ListBox
- Static image • Dynamic image
- Static text field
- Dynamic text field
- Edit field
- Slider
- Trend



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RHMI - AS6011.XXX

RHMI are a family of operator terminals, based on a fanless ARM processor suitable for producing simple but complete operator interfaces aimed to facilitate the use of the machine controlled by the end user. By using the RDT software, interaction is possible, through the BBC3 Protocol on support TCP / IP, with the motion controller connected both with variable exchange as well as with upload / download of files. The terminal is furthermore equipped with an integrated remote service software which renders its Internet access, particularly simple and quick.

HMI

Product specification:

• Display LCD TFT from 5.7 inches up to 15 inches

- CPU ARM Cortex A8 1 GHz fanless
- 512 MB Dynamic ram DDR3-800
- Removable SD card 1 GB hosting the application software • 256 MB NAND internal flash hosting the operating system • 2GB internal eMMC (Solid State Disk) hosting the system software • 2 USB ports
- 1 RS232/422/485 serial port
- Possibility to connect to an external keyboard/mouse
- 1 Ethernet interface 100 Mbits/s
- 1 Ethernet interface 10/100 Mbits/s
- Supplied from the 24VDC
- Microsoft Windows Embedded Compact 7 Pro (C7P)

Programming:

 RTM run-time software to execute RDT projects • REMOTE SERVICE software via VPN User friendly configurator

Programming:

• RTM run-time software to execute RDT projects REMOTE SERVICE software via VPN User friendly configurator

> Through these controls the user will be able to build the required project pages, to add actions, macros, help windows, to handle password levels, recipes, alarms history, multi-lingual facilities and many other utilities.

Each Robox motion controller can be associated to a serial device or a TCP/IP address thus allowing centralized diagnosis.

The resulting HMI application can run on any industrial PC, equipped with Windows or Linux operating system, through the RTM runtime software.

Human machine interfaces: HMI

Servo Drives



Drive dimensions at a glance

Dimensions (mm)	Frame 1	Frame 2	Frame 3
Width	40 mm	40 mm	40 mm
Depth	174 mm	174 mm	174 mm
Height	233 mm	278 mm	328 mm
Nominal current @ 400 V	1.5-3-4.2 A	6-8-10.5 A	13.5-16 A
Peak current @ 400 V	4.5-9-12.6 A	18-24-31.5 A	40.5-48 A



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ROBON

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Safety MiS250

Option Module for Advanced Safety to perform autonomously:

- Safe Stop 1 (SS1)
- Safe Stop 2 (SS2) • Safety Limited Speed (SLS)
- Safe Operating Stop (SOS)
- Safe Direction (SDI)
- Safe Speed Monitor (SSM)
- Safe Emercency Stop (SES)
- Safely Limited Position (SLP)
- Safely Limited Acceleration (SLA)
- Safe Brake Control (SBC)

Or via FSOE, using the SSCU programmable safety PLC, the Safe Limited Speed and Safe Limited Position at TCP level exploiting the SARC (Safe ARithmetic Calculations) power. See 'Programmabile Safety PLC' chapter.



SI-µPAC - AS3055.001

Motion controller able to control up to 32 axes, driven through EtherCAT fieldbus.

Main features:

- Microprocessor ARM Cortex A9 Single Core (600MHz)
- Memory:
- Micro SD flash memory
- 1 GB DRAM
- 512 Kbyte retentive memory ram for parameters and alarm history storage Communication:
- n. 1 10/100 Mbits/s Ethernet channels dedicated to Master fieldbus (EtherCAT CoE, SoE, EoE) for axes control and/or remote I/O
- n. 1 10/100 Mbits/s Ethernet channel for general purposes (TCP/IP, UDP, TFTP, Modbus/TCP, Ethernet/IP, Robox BCC/31/TCP)
- n. 1 USB-B-UART serial channel for general purposes (Robox BCC/31, DF1) Diagnostic web server
- O.P.C. Server, ActiveX, .Net Library, rLibQt, rLibJava e rLibC++ available for communication in Windows environment
- Remote service
- Real-time clock calendar

Programmable through RDE3 Development Environment.

Servo Drives



Servo Drives

INTEGRATED DRIVES NEARBY CONFIGURATION





RID20-E, RID20-IE Robox Integrated Drive - AS920X.01X

Product specification:

- Extremely compact dimensions 220 x 60 x 116 (mm) 1,5 kg
- Current, speed and position loop closed inside
- Up to 800 DC power supply
- Up to 2KW
- Auxiliary power supply 18-36 VDC
- Strong capability to support high temperatures and vibrations
- EtherCAT interface.
- Position transductor circuit configurable
- Safe Torque off circuits
- Holding brake control 24Vdc driving up to 0.7A
- Accelerometer for vibration analisys

Storage:

• Internal Flash memory 16MB

Communication:

- EtherCAT (CoE) (FoE) or CANopen DS402
- RS232 interface for developers

Transducers:

- Resolver
- Endat 2.1, 2.2, 3.0 (rotary/linear encoders)
- TamagawaSeiki (TS56xxNxx, SA35-17/33bit-PLS5V)
- SinCos (linear motor with SinCos transducer)
- SSI (rotary encoders)

• Hiperface DSL

BiSS-C

I/O's:

- 3 channels for digital I/O with speed, overcurrent threshold and function input/output, configurable **Connectors RID20-E:**
- Two hybrid connectors, receptacle angled rotatable, for power supply (800 V DC and auxiliary 18-36 V DC)
- Three M12 connectors, for digital I/O, serial interface, Safe Torque-Off signals
- One or two M15 connectors for motor phases and transducer cables (RID20-E Itec version)

Connectors RID20-IE

- Three PCB connectors, for power supply (800 V DC and auxiliary 18-36 V DC) and STO
- Two RJ45 connectors for EtherCAT network
- Three M12 connectors, for digital I/O, serial interface, Safe Torque-Off signals

Product codes

- RID20-E AS9201.013 (Degree of Protection: IP 67)
- RID20-E AS9201.014 (Degree of Protection: IP 67)
- RID20-IE AS9202.013 (Degree of Protection: IP 20)
- RID20-IE AS9202.014 (Degree of Protection: IP 20)

ROBOX MOTOR DRIVE

Drives information common to all the RMD.

- Up to 800 DC power supply
- Auxiliary power supply 18-36 VDC
- Strong capability to support high temperatures and vibrations



filter)

- 1 M12 connector, RS232 and Holding-brake button signals • 1 M12 connector, for input and output digital signals • 1 M12 connector, for torgue-off signals (local handle)









- Speed 3000 RPM

- Option brake

- One or two M15 connectors for motor phases and transducer cables (RID20-IE itec version)

INTEGRATED DRIVES



- Safety Torque-Off function (STO) selectable on the single drive or on all the drives in the chain
- Internal accelerometer for vibration analysis (3 Axes) • Diagnostics leds
- EtherCAT (CoE) (FoE) (Main Fieldbus Communication)
- RS232 interface (Local communication service)
- 2 digital inputs, IEC61131-2 type 1, 24VDC (with debounce
- 1 output/power-supply line (24VDC, up to 480mA), shortcircuit and overcurrent protected, can be cycled as slow digital output
- 2 HTEC hybrid connectors, with rotatable angled receptacle, for power supply (800 VDC and auxiliary 18-36 VDC), fieldbus and torque off (STO) signals (common for all the
- drives in the chain)

ROBOX MOTOR DRIVE 2.2NM (100DT)

• Speed 3000/4500/6000 RPM • Resolver/ENDAT 2.2 • Option absolute multiturn Option brake

ROBOX MOTOR DRIVE 3.2NM (100DT)

• Speed 3000/4500/6000 RPM • Resolver/ENDAT 2.2 • Option absolute multiturn • Option brake

ROBOX MOTOR DRIVE 7.2NM (100DT)

• Resolver/ENDAT 2.2 • Option absolute multiturn



SPECIAL PRODUCTS



> Robox motion controller μ RP-2



> Robox USB DONGLE AS3045.001



> SoM-2 System on Module 19513B.502



SINAMICS S120 Robox EtherCAT Interface





Robox motion controller µRP-2

In just 55x80x34 mm and an overall volume equal to almost 1/7 of its bigger brother (RP-2), it represents the goal of miniaturization, without sacrificing computing power.

It can be used in truly demanding applications with a high number of axes to control. It allows you to fully exploit the performance of the EtherCAT fieldbus.

Thanks to the integration of an Ethernet switch with 4 ports available externally, it guarantees maximum connectivity without the use of additional components.

AS1019.011 supports full compatibility with the wide range of AXIOLINE expansion modules. AS1019.001 for cold plate mounting

Robox USB DONGLE - AS3045,001

RP-2 axis control emulator for educational purposes or simulation stations.

ROBOX SoM-2 19513B.502

Product specification:

This SoM has the same CPU of RP-2/µRP-2 and can be used into a customized mother board. It can be programmed with RDE in the same way of RP-2/µRP-2.

SINAMICS S120 Robox EtherCAT Interface AS3031.005

Product specification:

- This board allows to interface the Sinamics S120 drive to an EtherCAT fieldbus as a slave device
- It is plugged in the appropriate slot of the CU320-2
- It allows multi-axis synchronous operation at a sync frequency ranging from 50Hz to 4KHz
- Position, velocity, torque modes and integrated positioner are provided
- When working in position, it interpolates the reference regardless of the master frequency
- UL Certification



SINAMICS S120 Robox CANopen Interface AS3031.002

Product specification:

- It allows to interface Sinamics drives to a CANopen DS301, DS402 fieldbus as a slave device
- It is plugged in the Sinamics in the appropriate slot
- It allows multi-axis synchronous operation at sync frequency ranging from 20 to 500Hz
- Position, velocity, torgue modes are provided
- When working in position control, it interpolates the reference at 1KHz regardless of the master frequency

SPECIAL PRODUCTS





RID20-E Shuttle configuration AS9201.011

The RID20-E Integrated Drive can be applied as shuttle configuration in customized rotary or linear motor up to 2kW. The specifications are the same of RID20-E NEARBY CONFIGURATION. The connections to the motor are realized through:

- 1 PPM SAMTEC connector for power motor phases
- 1 PMM SAMTEC connector for position motor transducer
- 1 PMM SAMTEC connector for holding brake
- 1 PMM SAMTEC connector for thermal motor sensor



SPECIAL PRODUCTS

Special products

AGV LINE



26



www.bertolottispa.com



www.mecfond.it



www.mpsengineering.it



www.gmebrasil.com.br



www.tecmas-monza.it

Inertial Guide System for AGV

The vehicle is controlled by a gyroscope able to measure its rotations around its vertical axis. Communication with the supervisor PC is obtained via WIFI.

The movement can be controlled by any Robox motion controller. By using the gyro information, the traction odometry and a precise detection of suitable magnets on the floor, the vehicle is driven, according to a map, inside the factory with a special algorythme implemented by using RDE development environment.

Robox has a complete software to manage one or many AGVs. Besides Inertial Magnetic Navigation, Robox offers laser triangulation and natural guidance (SLAM).

RHAM - AS3009.X14 magnet detector

Magnet detection device

- **Product specification:**
- 16x16 Hall sensor matrix
- Magnet position detected through a microcontroller integrated algorithm
- with 0.1 mm precision
- Communication with the Robox motion controller via EtherCAT
- Available with or without integrated gyro

AGV MANAGER

AGV MANAGER is a software tool running on Windows/Linux platforms, allowing to describe the plant operation for AGV's controlled by the Robox inertial guidance system.

- Communicates with the agv through:
 - Radio modem via serial link
 - wireless lan with protocol TCP/IP or UDP
- Communicates:
 - with PLC, through RS232 serial
 - with PLC, through an OPC server
 - with PLC, in ethernet with protocol send/receive or fetch/write
 - In a generic manner, through the reading/writing of files
- Communicates with the database:
 - SQL Server
 - MySql
 - PostgresSQL
- ODBC
- It is responsible for the movement of many AGVS simoultaneously:
 - handles automatically algorithmes of anticollision and priority among Agvs
 - Calculates automatically the best path to assign to each agv, by respecting the direction of the path and the Agv orientation, as defined in the plant map.
- It supplies an integrated development environment (x-script) to describe the Agvs movement behaviour
 - with great flexibility and adaptation to the peculiarities of each plant
 - without any need of external compiling tools
 - by processing the infos received through the AgvManager native interfaces or by exchanging information through other channels (socket,...)
 - it gives the possibility to integrate "plugin" specifically written for an application, to increase the specific functionality of AgvManager for the single plant



AGV LINE

RHAM - AS3009.X13 magnet detector

Magnet detection device **Product specification:**

- 16x4 Hall sensor matrix
- Magnet position detected through a microcontroller integrated algorithm
- with 0.1 mm precision Communication with the Robox motion controller via
- EtherCAT Available with or without integrated gyro





RAT is a software tool running on Windows/Linux platforms, allowing to describe the plant map for AGV's

Exploiting the possibility to import lay-outs in DXF format (both of the plant and of the vehicle) the user will draw the routes, customize their crossings, speeds, behaviour (bends, radius, speed or clockwise - counterclockwise rotation), start and load/unload points, etc.

RAT also allows to simulate the mission length or the dimension of the space occupied, in order to optimize the AGV operation.

AGV Manager and Robox AGV Tools



A fully integrated development environment that guides the users to design, develop, debug, delivery and install their software, for any field of application in motion control.











Robox Development **Environment**



RDE General Information

RDE basic functions:

- Allows to write, compile and debug the application software
- Permits to evaluate the behaviour of the controlled machine and therefore to choose the best solution to optimize it
- Allows to describe the controlled machine in a graphic form configuring the axes, the powersets and the robots geometrical structures
- Allows to describe the devices present in the fieldbuses
- Runs on personal computers with Microsoft Windows 10 (build 1803 and later)
- Communicates with the Motion Controllers via Ethernet (TCP/IP) or serial link
- Integrated electronic documentation

RDE offers the programmer the following languages to write the application software:

- Structured text with motion libraries (suitable for motion control applications) for ex. electric shafts, electronic cams, flying shears, axes tracking and gearing. Possibility to monitor and make "live" modifications of the program
- Structured text with robotics libraries (suitable to describe palletizing cycles, pick&place and paths in general, for ex: cutting, drawing, glueing etc...). Possibility to monitor and make "live" modifications of the program
- Ladder IEC1131 (suitable for plc programming) Possibility to monitor and make "live" modifications of the rungs
- ISO (interpreter of ISO sources generated by external CAD/CAM)
- PLCopen function blocks library
- OB, Object Blocks (extended concept of Function Block). They are available in the other Robox languages
- C++ allows the programmer to design his own OB in order to create his own libraries
- RPL Robot programming language
- R++ Object Oriented Programming Language

A modern object oriented structured text, that makes easier to develop application and user's libraries

RDE offers the programmer, for a user friendly debugging, the following tools:

- Oscilloscope (synchronous with the motion task)
- Monitor (to watch the variables values)
- Graphical panels (to realize cock-pits to debug the controlled machine)
- Breakpoints: on the execution of an instruction (stopping the execution or just counting the event occurrences), on a variable read operation, on a variable write operation
- Trace on tasks
- Step by step instructions (to follow the program flow)
- "live" modification (to modify LD/ST tasks without re-booting the system)
- 3D Graphical panels (for a virtual simulation of the controlled machine)
- Graphical panels to interact (display and edit) with the devices (drives) connected to the fieldbus

30

• System Monitor (allows the realtime monitoring of the main functionalities of the controlled machine)

Programming Languages

Structured text with MOTION libraries

It allows to easily approach the following problems:

- Solving synchronization problems for any number of rotating and/or translating axes
- Programming even sophisticated motion laws by simply writing their equations
- Building electronic cams
- Live modifications

List of some motion libraries

MV CAM MV_CRIMPER MV FOLLOW MV_PHASE_ADJ MV REACH TARGET MV_TO_N_CJ etc...

Execute a CAM Suitable for packaging machine Flying shear Phasing between two axes Axes tracking

Structured text with ROBOTICS libraries

- Fly move for pick&place applications etc...
- Continuous path control for cutting/glueing etc..
- Linear, circular, spline interpolation at the "tool point"
- ISO (interpreter of ISO sources generated by external CAD/CAM)

List of some Robotic libraries

MV FLY JOINT MV_FLY_CART MV_LINEAR MV SPLINE MV CIRC PE_EXEC_PATH

In the menu: project configurator

the user can easily:

- Parameterize the structure and the most relevant variables
- Parameterize the power handling using the power set configuration tool - Parameterize the alarms handling

The system is able to handle more than one axes group simultaneously etc...



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Ladder diagram

Suitable for PLC programming

- Complete list of elements (IEC61131)
- Monitor
- Live modifications (off-line and on-line)

OB use from LD

- Mathematical blocks
- OB full integration
- PLCopen Function Blocks Library

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OB

Object Blocks (extended concept of Function Block) are predefined CLASSES (ex: PID , MUX, BELT, PLC OPEN etc) which the user can instance in his project.

It is possible to use the methods offered by the class, invoking them from the other languages.

In the menu:

project \diamond configurator

the user can easily define the predefined OB's that he prefers to use, make instances, and configure its parameters.

Object Block (extended concept of Function Block) can be developed by the user to build his own classes of libraries

Starting with the definition of the interface (parameter and methods) it is possible to write any kind of software in C++, exploiting the power of the object oriented philosophy (a low level Interface is available with the operative system)

The OB developer can also modify an existing OB to add new features (properties, methods etc..) or use other existing OB's

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Graphical Configurators

The graphical configurator allows to describe both the hardware and software, easily and rapidly.

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RFBCED (Robox Fieldbus editor configurator) It allows to describe the EtherCAT net (PDO contents etc...)

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Axes group configurator

It allows to group the axes and make a selection from different kinematics etc.

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Machine Configurator It allows to describe an axis, a group of axes,

kinematics, a power set etc.

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RDE

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PLIBED (Path Library Editor)

It allows to edit and test the paths and points libraries

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COC (CANopen configurator)

It allows to describe the CANopen net (PDO contents etc...)

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Hardware configurator

It allows to select the Robox motion controller where the application will run.

RDE Debugging Tools





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RDE development environment graphic panel



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RDE Debugging Tools





RDE development environment system monitor

























Building trust together

Certificate

CISO/IMQ has issued an IONET recognized certificate that the organization

ROBOX SPA VIA SEMPIONE 82 - 28053 CASTELLETTO TICINO (NO) Italy

has implemented and mantains a Quality Management System

for the following scope: esign, management of production, installation, after-sale service of electronic equipment for industrial machinery control

which fulfills the requirements of the following standard: ISO 9001:2015

Issued on: Expires on:

2024/12/02 2027/12/29











How to reach us

GPS COORDINATES: LATITUDE 45° 43' 15" North-longitude 8° 37' 6" East It's very simple both from Milano, Torino and Genova directions. Leave the A8/A26 highway at Castelletto Ticino.



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